Spectrum Journal of Innovation, Reforms and Development	
Volume 29, July - 2024	ISSN (E): 2751-1731
Website: www.sjird.journalspark.c	org
EVALUATION OF ACCURAC	CY LEVEL OF GPS MONITORING SYSTEM
	INDICATORS
Ziyayev K	Camoliddin Zukhritdinovich
PhD., Docent of T	Sashkent State Transport University
Δ	Abduialilova M. B.
Student at Task	hkent State Transport University
	Yangiyeva I. I.
Student at Tash	nkent State Transport University
Abstract	
Operational characteristics of cars are	e directly related to its driving modes [1]. Determinin
the vehicle's average speed, acc	celeration and deceleration and improving the
characteristics under these conditions	s is an urgent issue.
Determining the driving modes of vel	hicles is currently carried out with the help of a wide
used CDS monitoring system [2] The	e nurnose of the study is to recommend the use of GP
used GPS monitoring system [2]. The	c purpose of the study is to recommend the use of of

Introduction

Primary test studies were conducted in the following order on the main ring road of Tashkent city and the streets of professors' town.

Purpose of the test: To master the methods of operation and calibration of the designed equipment and to evaluate and improve their level of accuracy.

Necessary equipment for testing: Nexia car equipped with 5th wheel mounting device; 5th wheel; GPS device; laptop; distance meter (dalnomer); Necessary equipment for the installation of the 5th wheel.

Test conditions and location: The test is conducted on a level road with little traffic. Since the accuracy of the GPS unit is affected by the turning of the vehicle and the slope of the road, it is necessary that the road consists of turns.

Test procedure:

- Preparing the vehicle for testing (installation of 5th wheel and GPS device);

- Preparation of a straight horizontal track with a measured distance (500 m depending on the conditions) for the calibration of the 5th wheel. The starting point of the straight road is marked by measuring the required distance using a distance meter;

– Calibrating the 5th wheel – the bearing surface of the 5th wheel is set to the initial mark. A calibration program is run on the laptop and the vehicle travels a measured distance at an arbitrary speed. It is important that the 5th wheel stops on the second line of the distance measured by the road support surface. During the calibration period, the rolling radius of the wheel is determined by



the number of teeth of the gear wheel detected by the sensor of the 5th wheel and loaded into the program. The accuracy of the calibration is compared to the program readings by driving the vehicle in the above manner over a measured distance. If the indicators match, the test can be continued on the car, otherwise the calibration will be repeated.

- Carrying out the main test - the car is driven on the test track for 30 minutes, covering different modes, turns and significant and continuous slopes (the time of the car's turning and movement on the slopes is recorded). In order to verify that the calibration parameters of the 5th wheel are saved, the car is driven on the road with a repeatedly measured distance.

Analysis of test results

- Initial assessment of the accuracy of the GPS device was carried out by the value of the total distance covered by the test program indicator, and the obtained data was uploaded to the Excel program.

The results of the conducted test were analyzed by the speed of the car and the traveled path over time (Fig. 1).



Figure 1. Preliminary test results to evaluate the accuracy level of the GPS device

As can be seen from Figure 1, the speed of the vehicle according to the data of the GPS device is low, but the change behavior is consistent with the speed detected by the 5th wheel. Therefore, the results of the GPS device were corrected by a correction factor.







As a result of the analysis, the determined speed indicator was found to be 1.778 times less, and the GPS system speed indicator was corrected (Figure 2). After adjusting the GPS speed indicator and zooming in time, it became clear that the GPS analysis results were late for a certain time (Figure 3), and the equipment was synchronized in time. After the calibration steps above, the GPS system speed reading error was found to be less than 2%.



Fig. 3 Calibration test results for estimating the accuracy level of the GPS device

Based on the above analysis and the conducted tests, it can be concluded that the level of accuracy of the GPS device is sufficient in the study of speed indicators in urban operating conditions.

REFERENCE:

- Abdurazzokov, U., Sattivaldiev, B., Khikmatov, R., & Ziyaeva, S. (2021a). Method for assessing the energy efficiency of a vehicle taking into account the load under operating conditions. E3S Web of Conferences, 264, 05033. https://doi.org/10.1051/e3sconf/202126405033
- Abdurazzokov, U., Sattivaldiev, B., Khikmatov, R., & Ziyaeva, S. (2021b). Method for assessing the energy efficiency of a vehicle taking into account the load under operating conditions. E3S Web of Conferences, 264, 05033. https://doi.org/10.1051/e3sconf/202126405033
- 3. Dashdamirov, F., Abdurrazzokov, U., Ziyaev, K., Verdiyev, T., & Javadli, U. (2023). Simulation testing of traffic flow delays in bus stop zone. E3S Web of Conferences, 401, 01070. https://doi.org/10.1051/e3sconf/202340101070
- Faizullaev, E. Z., Rakhmonov, A. S., Mukhtorjanov, U. M., Turdibekov, S., & Nasirjanov, Sh. I. (2023). Parameters of the access road for disaster situations on the roads in the mountain area. E3S Web of Conferences, 401, 03022. https://doi.org/10.1051/e3sconf/202340103022
- 5. Fayzullaev, E., Tursunbaev, B., Xakimov, S., & Rakhmonov, A. (2022). Problems of vehicle safety in mountainous areas and their scientific analysis. 030099. https://doi.org/10.1063/5.0089596
- Fayzullayev, E., Khakimov, S., Rakhmonov, A., Rajapova, S., & Rakhimbaev, Z. (2023). Traffic intensity on roads with big longitudinal slope in mountain conditions. E3S Web of Conferences, 401, 01073. https://doi.org/10.1051/e3sconf/202340101073
- 7. Ikromov, A. (2023). Components modifying methods with the using of energy technologies. 060037. https://doi.org/10.1063/5.0115559



- 8. Kasimov, O. (2023). Method for regulation of permissible irregularity of brake forces on front axle. E3S Web of Conferences, 401, 02033. https://doi.org/10.1051/e3sconf/202340102033
- 9. Kasimov, O., & Tukhtamishov, S. (2023). Mathematical model of braking process of car. E3S Web of Conferences, 401, 02034. https://doi.org/10.1051/e3sconf/202340102034
- Keldiyarova, M., Ruzimov, S., Bonfitto, A., & Mukhitdinov, A. (2022). Comparison of two control strategies for range extender hybrid electric vehicles. 2022 International Symposium on Electromobility (ISEM), 1–6. https://doi.org/10.1109/ISEM55847.2022.9976663
- Khakimov, S., Fayzullaev, E., Rakhmonov, A., & Samatov, R. (2021). Variation of reaction forces on the axles of the road train depending on road longitudinal slope. E3S Web of Conferences, 264, 05030. https://doi.org/10.1051/e3sconf/202126405030
- 12. Kulmukhamedov, Z., Khikmatov, R., Erbekov, S., & Saidumarov, A. (2022). Maximum temperature values of the engine and auto motor vehicles units in conditions of elevated ambient temperatures. 030040. https://doi.org/10.1063/5.0093466
- Kulmukhamedov, Z., Khikmatov, R., Saidumarov, A., & Kulmukhamedova, Y. (2021). Theoretical research of the external temperature influence on the traction and speed properties and the fuel economy of cargo-carrying vehicles. Journal of Applied Engineering Science, 19(1), 68–76. https://doi.org/10.5937/jaes0-27851
- Kutlimuratov, K., Khakimov, S., Mukhitdinov, A., & Samatov, R. (2021). Modelling traffic flow emissions at signalized intersection with PTV vissim. E3S Web of Conferences, 264, 02051. https://doi.org/10.1051/e3sconf/202126402051
- 15. Mavlonov, J., Ruzimov, S., Tonoli, A., Amati, N., & Mukhitdinov, A. (2023). Sensitivity Analysis of Electric Energy Consumption in Battery Electric Vehicles with Different Electric Motors. World Electric Vehicle Journal, 14(2), 36. https://doi.org/10.3390/wevj14020036
- Mukhitdinov, A., Abdurazzokov, U., Ziyaev, K., & Makhmudov, G. (2023). Method for assessing the vehicle energy efficiency on a driving cycle. 060028. https://doi.org/10.1063/5.0114531
- 17. Mukhitdinov, A., Ziyaev, K., Abdurazzokov, U., & Omarov, J. (2023). Creation of the driving cycle of the city of Tashkent by the synthesis method. 060029. https://doi.org/10.1063/5.0126363
- Mukhitdinov, A., Ziyaev, K., Omarov, J., & Ismoilova, S. (2021). Methodology of constructing driving cycles by the synthesis. E3S Web of Conferences, 264, 01033. https://doi.org/10.1051/e3sconf/202126401033
- 19. Nurmetov, K., Riskulov, A., & Ikromov, A. (2022). Physicochemical aspects of polymer composites technology with activated modifiers. 020011. https://doi.org/10.1063/5.0106358
- Sanjarbek, R., Mavlonov, J., & Mukhitdinov, A. (2022). Analysis of the Powertrain Component Size of Electrified Vehicles Commercially Available on the Market. Communications - Scientific Letters of the University of Zilina, 24(1), B74–B86. https://doi.org/10.26552/com.C.2022.1.B74-B86
- 21. Topalidi, V., Yusupov, U., & Allaberganov, S. (2022). Improving the efficiency of transport logistics support. 030072. https://doi.org/10.1063/5.0089587
- 22. Tursunov, S., & Khikmatov, R. (2023). Increasing environmental safety, increasing service life of ice units and assembly and saving fuel consumption through application of multifunctional fuel additives. E3S Web of Conferences, 365, 01012. https://doi.org/10.1051/e3sconf/202336501012



- 23. Usmanov, U., Ruzimov, S., Tonoli, A., & Mukhitdinov, A. (2023). Modeling, Simulation and Control Strategy Optimization of Fuel Cell Hybrid Electric Vehicle. Vehicles, 5(2), 464–481. https://doi.org/10.3390/vehicles5020026
- 24. Yusupov, U., Kasimov, O., & Anvarjonov, A. (2022). Research of the resource of tires of rotary buses in career conditions. 030073. https://doi.org/10.1063:/5.0089590
- Yusupov, U., & Mukhitdinov, A. (2023). Evaluation of the influence of the longitudinal slope of carriage roads on the tire life. E3S Web of Conferences, 401, 03025. https://doi.org/10.1051/e3sconf/202340103025
- 26. Avdeychik, S., Goldade, V., Struk, V., Antonov, A., & Ikromov, A. (2020). THE PHENOMENON OF NANOSTATE IN MATERIAL SCIENCE OF FUNCTIONAL COMPOSITES BASED ON INDUSTRIAL POLYMERS. Theoretical & Applied Science, (7), 101-107.
- 27. Ziyaev K, Omarov J, Research of passenger traffic in public transport, AIP Conference Proceedings, 2024, 3045(1), 040030, DOI: 10.1063/5.0197314
- 28. Mukhitdinov, A., Yusupov, U., Tukhtamishov, S., Urinbayev, Q., Results of the study of the influence of an average longitudinal slope of routes on the life of tires in the quarry, AIP Conference Proceedings, 2024, 3045(1), 040041, DO:I10.1063/5.0197301
- 29. Abdurazzoqov, U., Anvarjonov, A., State of transport system organization in developed cities, AIP Conference Proceedings, 2024, 3045(1), 040012, DOI:10.1063/5.0197302
- 30. Tursunov, S.R., Sharipov, S.S., Khikmatov, R.S. Saving natural gas through the use of used oils in replacement by the method of their safe burning, AIP Conference Proceedings, 2024, 3045(1), 050022, DOI:10.1063/5.0197545
- Tursunov, S.R., Khikmatov, R.S., Khusanov, S.N.-U., Increasing the efficiency of the use of mining transport due to increasing the periodicity of maintenance time, AIP Conference Proceedings, 2024, 3045(1), 050021, DOI:10.1063/5.0197547.